

21st Transport Sector Coordinating Committee Meeting

22-23 April 2024 • Almaty, Kazakhstan

21-е заседание Координационного комитета по транспортному сектору

22-23 апреля 2024 года • Алматы, Казахстан

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Big Data, Artificial Intelligence and Digitalization

Dr. S. Travis Waller

Managing Director Mobility Thinking Pty Ltd **Evolution of Transport Modeling to Support Planning**

Emergence of Big Data / Pervasive Data

Alternatives to traditional sources Potential for exponential acceleration, also challenges (format, substance)

Advanced Statistical and Machine Learning AI Tools

Potential to automated traditionally labour-intensive tasks New skillsets and specialists required but need to understand planning

Increased Need for Openness, Equity and Sustainability

Drives new quantification and broader metrics (EJ, Equity, Resilience) We must free up our time to expand what we can do (eliminate repetitive)

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To Look Forward, Let's First Quickly Glance Back

- What has formed the noted view?
- During my relocation to Germany in 2022
 - I reflected on my relocation from Austin(Texas) to Sydney(Australia) in 2011
- I was working on 4 topics prior to 2011 that are still ongoing today
- The exact 2011 slides and some outcomes are briefly shown



Past and ongoing clients/sponsors including:

NVIDIA, Asian Development Bank, U.S. National Science Foundation, Australia Research Council, U.S. Federal Highway Administration, U.S. DOT, TfNSW, Mitsubishi Heavy Industries, Advisian, GoGet Carshare in addition to many other government agencies, software companies, infrastructure firms, advisory firms, banks, insurance companies, startups, etc.

1. Electric Vehicles

Very early research in the area of

Studying the future behavior of travelers with the emerging reality of electric vehicles

The work requires a blending of topics spanning human behavior, technology, and emerging data

Our work began on this topic in 2007

Collaborative with Dr. Mladen Kezunovic (Global Expert on Power Systems, NAE Member)

The established NSF Center was pioneering in the EV domain and our work on the topic has continued through today

Center for Transportation and Electricity Convergence

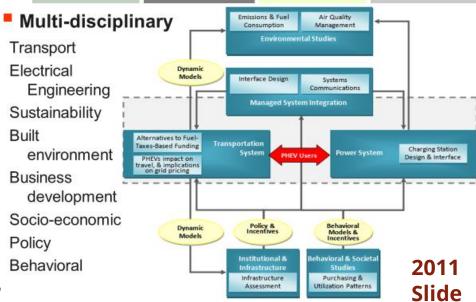
Awarded August, 2010

- UT-Austin lead with Texas A&M
 - · Additional universities and agencies/companies planning to join
- National Science Foundation Industry and University Cooperative Research Center (NSF IUCRC)
- Renewable up to 15+ years, approx. \$7.5M+

Industry/agency members include:



Research Overview



2. Environmental Justice Across Protected Groups

We provided the first quantification of EJ for Transport Network Modelling and Planning in the literature (2008)

With my former PhD student, Dr. Jen Duthie (now head of Innovation for Cintra, one of the largest private developer of transport infrastructure globally)

Requires new forms of data and synthesis that include social values

The study won the U.S. Transportation Research Board Fred Burggraf Award

TRB is a division of the US National Academy of Science, Engineering and Medicine

While the work was mathematical in nature, it was also highly practical for usage

Used by one of the largest planning organization in the US

Kicked off a stream of activity through present day

Environmental Justice, Emissions, Sustainability and Uncertainty

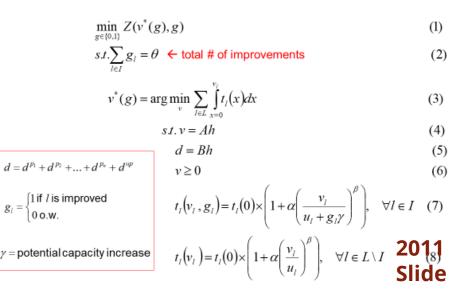
- Quantifiable engineering tools for properly accounting for
 - Environmental justice considerations
 - Optimizing network improvements for emission reduction
 - Sustainable planning accounting for uncertainty

Sponsors

| North Central Texas Council of Governments (Dallas | MPO) |
|--|-------|
| Southwestern University Transportation Center | |
| National Science Foundation | 2011 |
| FHWA | Slide |

Definitions difficult. One EJ variation is: **Avoid disproportionality** and maintain/improve access for protected groups

EJ-UE-DNDP



3. Study of Disease Spreading in Transport Networks

We began studying the spread of disease through transport networks very early (2005 onward)

Especially with novel emerging big-data

PhD (2011) thesis topic of Dr. Lauren Gardner (my former PhD student at UT Austin and mentored colleague at rCITI, UNSW 2011-2019).

Dr. Gardner would go on to create the well-known COVID19 Dashboard after her relocation to Johns Hopkins University in 2019 (and to be named to the list of TIME's 100 most influential people in the world of 2020).

Epidemiology and Transport

- Collaborative with
 - Prof. Sahotra Sarkar (Integrative Biology)
 - Dr. Lauren Gardner
- Ecological, transport, water networks
- Current proposal efforts for
 - National Institute of Health
 - National Science Foundation
 - Airport Cooperative Research Program
 - Bill and Melinda Gates Foundation

Example from work $f_{3A}(\lambda, X_3, Y_A, Z_{3A})$ evaluating risk related to Dengue from Air Travel (network-level regression)

Set of Endemic Countrie

f 1A (2, X1, YAZ1A)

 $f_{2A}(\lambda, X_2, Y_A, Z_{2A})$

Set of Susceptible U.S. State set of Susceptible E.U. Count

2011

Slide

Initiated activity to better understand disciplinary impacts and interactions of mobility

4. Automated/Autonomous Vehicles

Beginning from work in 2006, jointly conducted first large (over \$1.8m) project globally to study

How AVs would function in a transport system

Computationally complex with travel behavior changes (machine learning, early AI work)

This project was collaborative work with Computer Science Professor Peter Stone

Co-founder of Cogitai, Inc. and now Executive Director of Sony AI America

Began long series of activities spanning many studies and projects including for government agencies, advisories, banks, insurance firms, etc.

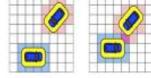
Automated/Autonomous Vehicles

- US FHWA Project: FHWA-PROJ-07-0026
- Intersection control for AVs
- 2007 2013
- Approx. \$2M research budget

One of the first functional system evaluations for autonomous vehicles



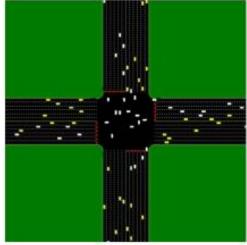
V2V and/or V



V2V and/or V2I reservation system

image MARVIN, automated vehicle at the University of Texas at Austin, developed by co-researchers





2011 Slide

The Present and Future: Evolution and Progress

From these emerging topics (all starting before 2010):

- 1. Electric Vehicles (leading onto broader e-mobility)
- 2. Environmental Justice Including Impact Across Protected Groups
- 3. Pandemics in Transport Networks
- 4. Automated/Autonomous Vehicles

For the topics of today we need to leverage lessons learned including new methodologies on

Emerging novel big-data

Machine Learning (Applied AI)

While including travel network behavior

All of this while incorporating more capacity to quantify social values

| Lille | rgence of Big Data / Pervasive Data Alternatives to traditional sources Potential for exponential acceleration, also challenges (format, substance |
|-------|---|
| Adva | nced Statistical and Machine Learning Al Tools Potential to automated traditionally labour-intensive tasks New skillsets and specialists required but need to understand planning |
| Incre | ased Need for Openness, Equity and Sustainability Drives new quantification and broader metrics (EJ, Equity, Resilience) We must free up our time to expand what we can do (eliminate repetitive) |



Ο

Impact on Transportation Planning

Covered by earlier talk

In short, opportunities include

To cut the time and cost dramatically

Standardize across regions

Increase transparency and engagement

Incorporate novel metrics

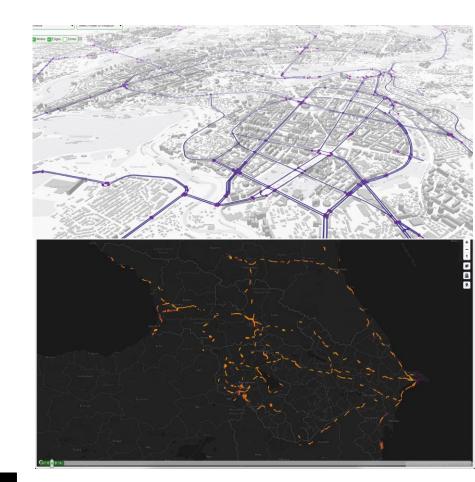
- Equity
- Sustainability
- Environmental impact/justice
- Resilience
- Etc.

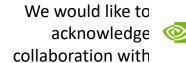
Critical Note:

In doing all of this, we must not lose the capacity to appropriately model "what-if" scenarios.

If we lose this, we lose our purpose in the planning process.

To plan is not simply to analyse. It is not just data analytics.







Safety and Technology

- Technology changes travel behavior
 - Critical implications for planning

- We need to understand the safety impact of emerging technology to plan better
 - AVs, e-mobility, micromobility

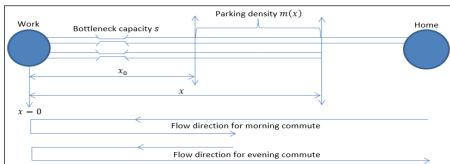
Also, using the new tools to **estimate safety in real-time**



N Virdi;H Grzybowska;ST Waller;V Dixit (2019) 'A safety assessment of mixed fleets with Connected and Autonomous Vehicles using the Surrogate Safety Assessment Module', Accident Analysis and Prevention, Vol 131, pp. 95-111.

E Qiu; N Virdi; H Grzybowska; ST Waller (2022) 'Recalibration of the BPR function for the strategic modelling of connected and autonomous vehicles', Transportmetrica B: transport dynamics 10 (1), pp. 779-800.

X Zhang; E Robson; ST Waller (2020) ' An integrated transport and economic equilibrium model for autonomous transportation systems considering parking behavior ' Computer-Aided Civil and Infrastructure Engineering, vol 36(7), pp 902-921.



Road Vehicle Carbon and Emission Modelling (Ongoing Work)

With the new data and methods, metrics can be more readily calculated

Example: Road vehicle carbon

3 Methods examined including:

Method #1:

Utilizing the fitted fourth-order polynomial equation (Barth equation).

Where y is CO2 emissions in g/mi, and x is the average trip speed in mph.

Barth, M., & Boriboonsomsin, K. (2008). Real-world carbon dioxide impacts of traffic congestion. Transportation research record, 2058(1), 163-171.

Comparison to the International Energy Agency (IEA) Report for CO₂ emissions London: IEA: UK road transport emissions are 114 million tonnes per year 312k tonnes per day, nationally Using a common peak-hour factor of 10 (i.e., two 3-hour peak periods, 4 off-peak)

Jsing a common peak-nour factor of 10 (i.e., two 3-nour peak periods, 4 off-pe

The Automated London *city model* reports **<u>2.9k</u>** tonnes for a specific 8-9am case Approximately 9.3% of UK road carbon per peak hour

Auckland:

IEA: New Zealand road transport emissions are 14.3 million tonnes per year 3.9k tonnes per peak hour

The automated Auckland city model reports **778** tonnes for a specific 8-9 am case Approximately 19.85% of New Zealand's road carbon per peak hour

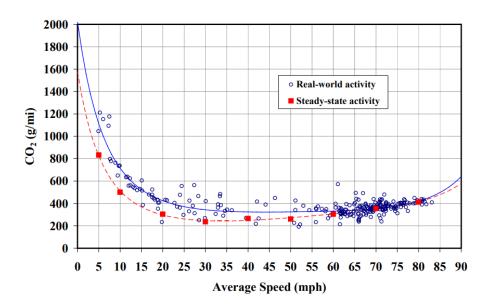


Table 1. Derived line-fit parameters for Eqn. (1)

 $\ln(y) = b_0 + b_1 \cdot x + b_2 \cdot x^2 + b_3 \cdot x^3 + b_4 \cdot x^4$

| | Real-World |
|-----------------------|---------------------|
| Ν | 241 |
| \mathbf{R}^2 | 0.668 |
| b ₀ | 7.613534994965560 |
| b ₁ | - 0.138565467462594 |
| b ₂ | 0.003915102063854 |
| b ₃ | - 0.000049451361017 |
| b ₄ | 0.00000238630156 |

red outside ADB with appropriate permission

Methods 2 and 3 for road carbon estimation

Method 2: Similar to Barth approach though volume-capacity ratios referenced.

Tsanakas, N., Ekström, J., & Olstam, J. (2017). Reduction of errors when estimating emissions based on static traffic model outputs. Transportation research procedia, 22, 440-449.

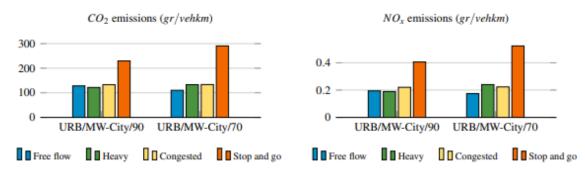


Figure 1. HBEFA emission factors; (a) CO2 (b) NOx.

Table 1. Volume/Capacity ratio thresholds.

| Speed limit (km/h) | Free flow | Heavy | Congested | Stop and go |
|--------------------|-----------|-----------------------|-----------------------|----------------|
| 90 | V/C <0.65 | $0.65 \le V/C < 0.85$ | $0.85 \le V/C < 1.35$ | $V/C \ge 1.35$ |
| 70 | V/C <0.39 | $0.39 \le V/C < 0.84$ | $0.84 \le V/C < 1.35$ | $V/C \ge 1.35$ |
| <50 | V/C <0.52 | $0.65 \le V/C < 0.78$ | $0.65 \le V/C < 1.22$ | $V/C \ge 1.22$ |

Method 3: uses a MOVES function (U.S. Environmental Protection Agency 2014) to model energy consumption alongside BPR to model link performance function:

BPR function:

$$t_{ij} = t_{ij}^0 \cdot \left(1 + \alpha \left(\frac{x_{ij}}{c_{ij}}\right)^{eta}\right) \quad \forall (i,j) \in A$$
 (1)

MOVES function:

$$\begin{cases} LTEC_{ij} = TEC_{ij} \cdot L_{ij} \\ TEC_{ij} = 9.9 \cdot S_{ij}^{-0.56} \end{cases} \quad \forall (i,j) \in A \end{cases}$$

$$(2)$$

where TEC_{ij} is the transport energy consumption rate per vehicle kilometre travelled on link (i, j), which is measured in kWh/km if the dimension of speed S_{ij} is km/h. By substituting the BPR function into Formula (2), the TEC_{ij} function becomes:

We employed this approach in this study:

Zhang, X., & Waller, S. T. (2019). Implications of link-based equity objectives on transportation network design problem. Transportation, 46(5), 1559-158

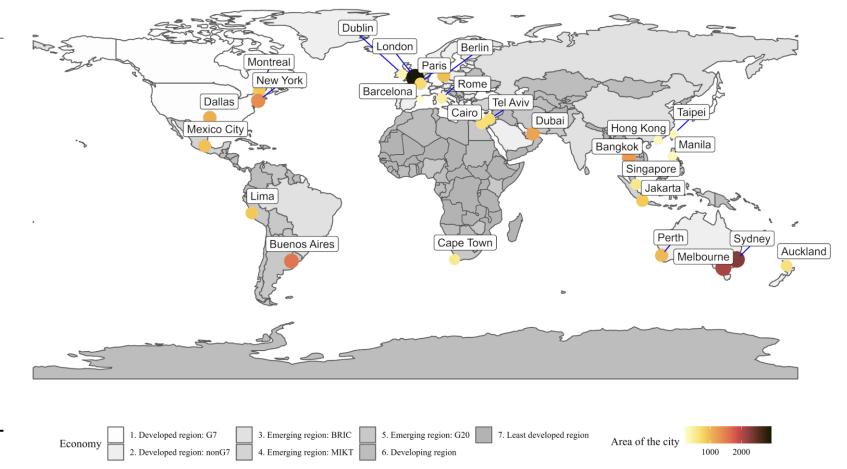
Considered World Cities

| City | Region | ¹ Economic | ² Area of |
|---------------------|-----------------|-----------------------|----------------------|
| - | - | Representation | city $[km^2]$ |
| Auckland | Oceania | Developed : Non G7 | 645 |
| Bangkok | Asia | Emerging : G20 | 1267 |
| Barcelona | Europe | Developed : G7 | 201 |
| Berlin | Europe | Developed : G7 | 954 |
| Buenos Aires | South America | Emerging : G20 | 1571 |
| Cairo | Africa | Emerging : G20 | 657 |
| Cape Town | Africa | Emerging : G20 | 540 |
| Dallas | North America | Developed :G7 | 1091 |
| Dubai | Middle East | Developing | 1159 |
| Dublin | Europe | Developed :G7 | 360 |
| Hong Kong * | Asia | Emerging : BRIC | 281 |
| Jakarta | South East Asia | Emerging : MIKT | 860 |
| Lima | South America | Emerging : G20 | 880 |
| London | Europe | Developed : G7 | 2961 |
| Manila | South East Asia | Emerging : G20 | 313 |
| Melbourne | Australia | Developed : Non G7 | 2103 |
| Mexico City | South America | Emerging : MIKT | 931 |
| Montreal | North America | Developed : G7 | 890 |
| New York | North America | Developed : G7 | 1388 |
| Paris | Europe | Developed : G7 | 717 |
| Perth | Australia | Developed : Non G7 | 1008 |
| Rome | Europe | Developed : G7 | 452 |
| Singapore * | Asia | Developing | 556 |
| Sydney | Europe | Developed : Non G7 | 2305 |
| Taipei | Asia | Developed : Non G7 | 273 |
| Tel Aviv | Middle East | Developed : Non G7 | 681 |

¹ Data Source: World Bank [4]

² Area of the city considered in the study through GIS mapping

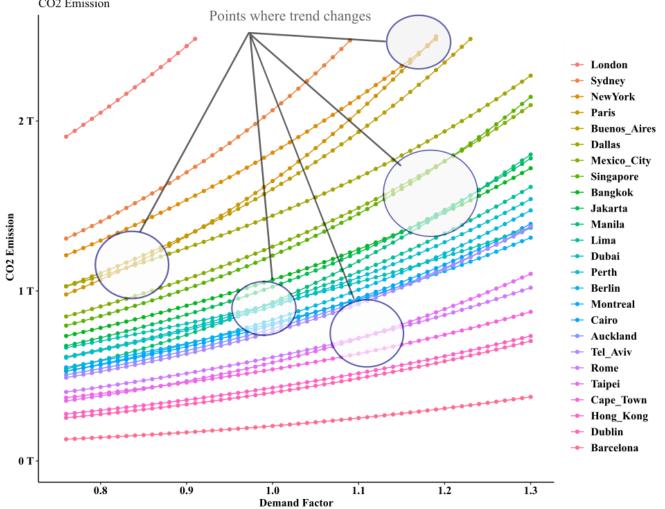
* Considered as developed economies based on the high GDP



Data source: World Bank

Quantification of the Gradient of Road Traffic Carbon (Carbon Sensitivity)

- The approach embeds a (travel demand)-(network supply) equilibrium
- This facilitates examination across numerous demand scenarios
- As a result, the gradient of road traffic carbon can be quantified
 - This allows for a different lens on city to city comparison



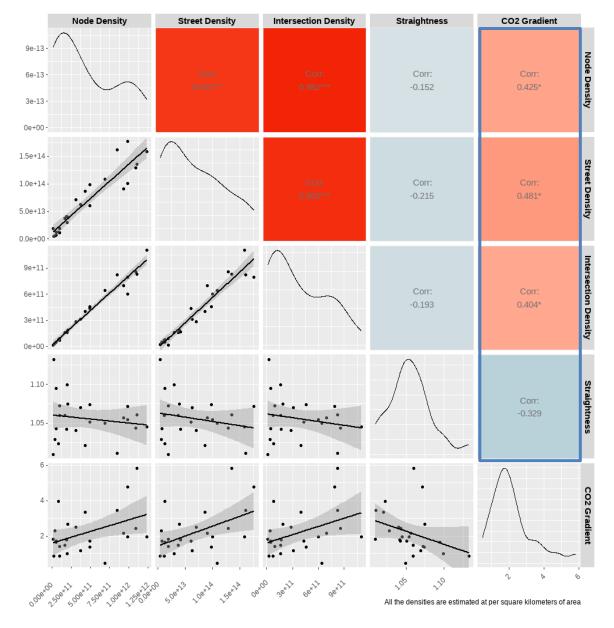
Do network parameters have any influence on gradient of emissions?

More than 25 different networks parameters were investigated

Defining size, shape, capacity, and orientation of road networks in world cities

<u>Preliminary Analysis</u>: 4 are found to have significant relation with gradient of emission

(i) Street Density (per km)
(ii) Node Density (per km)
(iii) Intersection Density (per km)
(iv) Straightness / Circuity



Duthie and Waller (2008) on Metrics for Environmental Justice

Similarly new metrics on equity and environmental justice can be calculated

Mandate: Respond to U.S. Presidential Order to use Environmental Justice in infrastructure planning

Agency needed a quantified method of incorporating novel concept for them

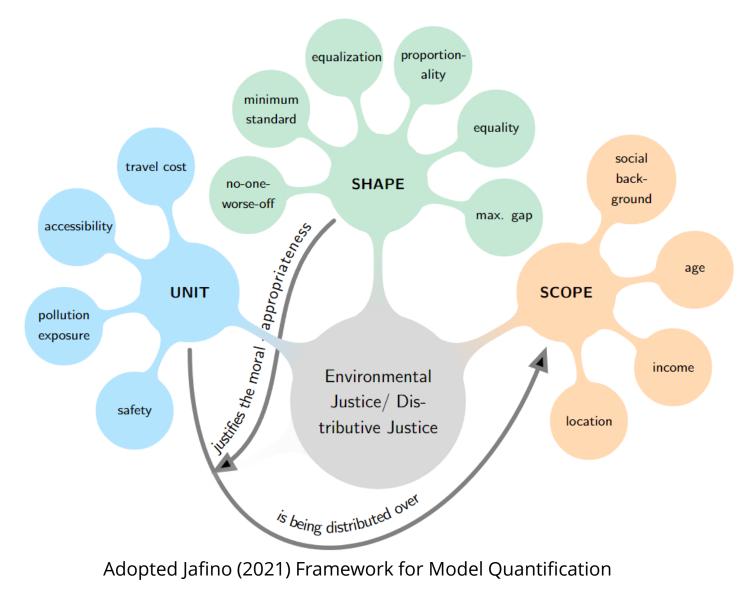
An early example of digitizing our emerging values into the formalized planning process

| $\min_{g\in[0,1]} Z\Big(v^*(g),g\Big)$ | (1) | $Z_1 = \frac{\sum\limits_{ij} s^t_{ij} d_{ij} p_{ij} / e^t_{ij}}{\sum\limits_{ij} d_{ij} p_{ij}}; \qquad \qquad Z_2 = \frac{\sum\limits_{ij} s^t_{ij} d_{ij} / e^t_{ij}}{\sum\limits_{ij} d_{ij}};$ |
|--|------------|---|
| subject to $\sum_{l \in L \setminus I} g_l = \theta$ | (2) | $Z_{3} = \left(\frac{\sum_{ij} s_{ij}^{t} d_{ij} p_{ij} / e_{ij}^{t}}{\sum_{j} d_{ij} p_{j}} - \frac{\sum_{ij} s_{ij}^{t} d_{ij} (1 - p_{ij}) / e_{ij}^{t}}{\sum_{ij} d_{ij} (1 - p_{ij})}\right)^{2};$ |
| $v^{*}(g) = \arg\min_{v} \sum_{l \in L} \int_{x=0}^{v_{l}} t_{l}(x) dx$ subject to | (3) | $Z_{4} = \left(\frac{\sum_{ij} \left(s_{ij}^{f} d_{ij} p_{ij} / e_{ij}^{f} - s_{ij}^{0} d_{ij} p_{ij} / e_{ij}^{0}\right)^{2}}{\sum_{ij} d_{ij} p_{ij}} - \frac{\sum_{ij} \left(s_{ij}^{f} d_{ij} (1 - p_{ij}) / e_{ij}^{f} - s_{ij}^{0} d_{ij} (1 - p_{ij}) / e_{ij}^{0}\right)^{2}}{\sum_{ij} d_{ij} (1 - p_{ij})}\right)^{2};$ |
| v = Ah d = Bh | (4) (5) | ${\mathcal Z}_5 = rac{\displaystyle \sum_{ij} s^f_{ij} d_{ij} ho_{ij}}{\displaystyle \sum_{ij} d_{ij} ho_{ij}}; \qquad \qquad {\mathcal Z}_6 = rac{\displaystyle \sum_{ij} s^f_{ij} d_{ij}}{\displaystyle \sum_{ij} d_{ij}};$ |
| $v \ge 0$ $t_l(v_l, g_l) = t_l(0) \times \left(1 + \alpha \left(\frac{v_l}{u_l + g_l}\right)^{\beta}\right) \qquad \forall l \in I$ | (6) (7) | $Z_{7} = \left(\frac{\sum_{ij} s_{ij}^{t} d_{ij} p_{ij}}{\sum_{ij} d_{ij} p_{ij}} - \frac{\sum_{ij} s_{ij}^{t} d_{ij} (1 - p_{ij})}{\sum_{ij} d_{ij} (1 - p_{ij})}\right)^{2};$ |
| $t_{l}(\mathbf{v}_{l}) = t_{l}(0) \times \left(1 + \alpha \left(\frac{\mathbf{v}_{l}}{u_{l}}\right)^{\beta}\right) \qquad \forall l \in L \setminus I$ | (8) | $Z_{8} = \left(\frac{\sum_{ij} \left(s_{ij}^{f} d_{ij} p_{ij} - s_{ij}^{0} d_{ij} p_{ij}\right)^{2}}{\sum_{ij} d_{ij} p_{ij}} - \frac{\sum_{ij} \left(s_{ij}^{f} d_{ij} (1 - p_{ij}) - s_{ij}^{0} d_{ij} (1 - p_{ij})\right)^{2}}{\sum_{ij} d_{ij} (1 - p_{ij})}\right)^{2}$ |

| TABLE 2 | Range | of Fitness | and | Number |
|------------|---------|------------|-----|--------|
| of Generat | ions to | Convergen | ce | |

| Objective Function | Z^{\min} | Z^{\max} | $n_{\rm converge}$ |
|-----------------------|-----------------------|-----------------------|--------------------|
| Z_1 | 1.98 | 2.31 | 7 |
| Z_2 | 1.99 | 2.23 | 6 |
| Z_3 | 4.00×10^{-5} | 8.52×10^{-4} | 17 |
| Z_4 | 0.44 | 206.08 | 29 |
| Z_5 | 3.91 | 4.45 | 5 |
| Z_6 | 3.98 | 4.51 | 5 |
| Z_7 | 5.27×10^{-3} | 8.90×10^{-3} | 16 |
| Z_8 | 8.06 | 2,480.51 | 12 |

Our Current Work in Germany, Australia and Hong Kong



Developing methods to incorporate varying measures for equity and justice into automated transport modeling tools

| Equity Measurement | Formulation |
|---------------------------------|---|
| Rawl's Egalitarian (RE) | $RE=\max\sum_{i=1}^k Y_i$ |
| Utilitarianism (U) | $U = \max \sum_{i=1}^{n} Y_i$ |
| Gini index (GINI) | $GINI = \frac{1}{2n^2\bar{Y}}\sum_{i=1}^n\sum_{j=1}^n Y_i-Y_j $ |
| Theil index (THEIL) | $THEIL = \frac{1}{n} \sum_{i=1}^{n} \left(\frac{Y_i}{\bar{Y}} \log \log \frac{Y_i}{\bar{Y}} \right)$ |
| Atkinson index (ATK) | $ATK = \begin{cases} 1 - \left[\frac{1}{n}\sum_{i=1}^{n} \left(\frac{Y_{i}}{\bar{Y}}\right)^{1-\epsilon}\right] \frac{1}{1-\epsilon}, \epsilon \neq 1\\ 1 - \frac{1}{\bar{Y}} \left(\prod_{i=1}^{n} Y_{i}\right)^{\bar{n}}, \epsilon = 1 \end{cases}$ |
| Sadr's theory of Justice (SADR) | $SADR = \begin{cases} \max \sum_{i=1}^{n} Y_i; \\ s.t \ Y_i > m1 \times Y_j, \forall i, j \\ \sum_{i,j} \frac{Y_i - Y_j}{2n^2 \bar{Y}} < m2 \end{cases}$ |
| Relative mean deviation (RMED) | $RMED = \frac{1}{n} \sum_{i=1}^{n} \frac{Y_i}{\bar{Y}} - 1 $ |
| Mean log deviation (LDEV) | $LDEV = \frac{1}{n} \sum_{i=1}^{n} \log \log Y_i - \log \log \overline{Y} $ |

Planning, Equity and Resilience

- Quantifying metrics is not sufficient
- We must plan, including for resilience
- Resilience planning absolutely requires hypothetical analysis
 - It is all about the potential future disrupted phase
- Ultimately, this requires a synthesis
 - New data
 - New methods
 - Traditional principles of transport planning

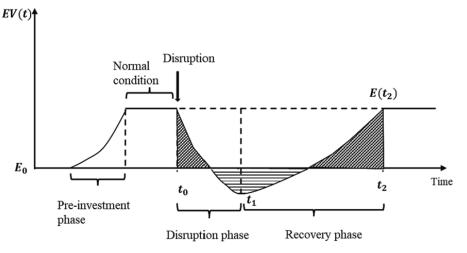


Fig. 1. Economic-based Network Resilience Measurement with a pre-investment project.

T Zhang, C Niu, D Nair, V Dixit, and ST Waller (2023) 'Equity analysis and improvement in transportation resilience optimisation at the pre-event stage' Transportation Research Part D: Transport and Environment, Vol 122, pp 1-24.





Summary

Emerging big data and Machine Learning/Applied AI have dramatic potential

Significant developments have already been made Many more remain

But, we must appropriately integrate these emerging tools into the principles of our professional domain

We have a process though

Use emerging tools to first quantify, measure, make metrics

Modify the planning tools to employ these new metrics

Automate as many repetitive steps as we can

